- If the complete structure is recognized, but of poor quality, a conventional Fourier synthesis may be used to obtain refined parameters.
- If only a fragment is recognized (say less than $60 \%$ of the total scattering power), this fragment may be used as input to DIRDIF.
- If the structure is not recognized, one should pay attention to the printed statistical quantities, and examine the input model. Large $B_{p}$ and small $p_{\text {exp }}^{2}$ indicate a bad model. Too large or too small $B_{r}$ values or an $\left|E_{r}\right|^{2}$ average which deviates too much from unity are often related to scaling problems: in this case the user may supply reasonable values for $B_{p}$ and $B_{r}$ and rerun $D I R D I F$ with a severe $\sin \theta / \lambda$ cut-off. The following rerun options may be considered:
* If the model consists of one or more heavy atoms, which appear to be shifted by more than $0.1 \AA$, the new positions may be used as input.
* For a light-atom fragment the same option can be applied and one may also reject the atoms that return low in the peak list, and include some higher peaks.
* If the input fragment completely returns in the $D I R D I F$ Fourier, with atomic shifts less than $0.1 \AA$, we suggest adding a number of high peaks to the known fragment: this number may be $10,20 \%$ of the total number of non-hydrogen atoms, or $50 \%$ of the number of atoms of the input model, depending on the problem at hand.

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# General Lattice Factor of the Ideal Paracrystal 

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#### Abstract

The lattice factor of a paracrystalline lattice with oblique axes and with general orientation of the fluctuation tensor ellipsoid is calculated. Directly applicable formulas for the special case of a monoclinic (macro) lattice, which is of interest in connexion with the small-angle scattering of oriented semicrystalline polymers, are given.


## 1. Introduction

The ideal paracrystal is a model of a statistical distorted crystal lattice or macro lattice (Hosemann \&

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Bagchi, 1962). The distortions are described by the cell-edge statistics $H_{k}(\mathbf{x})(k=1,2,3)$ and the mean cell-edge vectors are

$$
\begin{equation*}
\mathbf{a}_{k}=\int \mathbf{x} H_{k}(\mathbf{x}) \mathrm{d}^{3} \mathbf{x} \tag{1}
\end{equation*}
$$

For statistics $H_{k}(\mathbf{x})$ having a center of symmetry, the statistical amplitude $F_{K}(\mathbf{b})$, the Fourier transform, . $F\left\{H_{k}(\mathbf{x})\right\}$, can be expressed in the form

$$
\begin{equation*}
\left.F_{k}(\mathbf{b})=\left|F_{k}(\mathbf{b})\right| \exp \mid-2 \pi i \mathbf{b} \cdot \mathbf{a}_{k}\right] \tag{2}
\end{equation*}
$$

where, for statistics $H_{k}(\mathbf{x})$ Gaussian (otherwise as an approximation),

$$
\begin{equation*}
\left.\left|F_{k}(\mathbf{b})\right|=\exp \mid-2 \pi^{2} \mathbf{b} \cdot \mathbf{T}(k) \cdot \mathbf{b}\right] \tag{3}
\end{equation*}
$$

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The analytical part of the lattice factor is given by

$$
\begin{equation*}
Z(\mathbf{b})=\prod_{k=1}^{3} \frac{1-\left|F_{k}(\mathbf{b})\right|^{2}}{\left[1-\left|F_{k}(\mathbf{b})\right|\right]^{2}+4\left|F_{k}(\mathbf{b})\right| \sin ^{2}\left[\pi\left(\mathbf{b} \cdot \mathbf{a}_{k}\right)\right]} \tag{4}
\end{equation*}
$$

The principal values of the three symmetric fluctuation tensors $T(k)$, with regard to orthogonal coordinate systems $\stackrel{\circ}{e}_{j}(k)$ parallel to the directions of the principal axes (Fig. 1), are

$$
\begin{equation*}
d_{j j}^{2}(k)=\int\left[\dot{\mathbf{e}}_{j}(k) .\left(\mathbf{x}-\mathbf{a}_{k}\right)\right]^{2} H_{k}(\mathbf{x}) \mathrm{d}^{3} \mathbf{x} \tag{5}
\end{equation*}
$$

The principal axes of these tensors in general do not coincide with the crystallographic axes $\mathbf{a}_{k}$.

The distortion of the paracrystal is defined by the nine values $\dot{J}_{j j}(k)$ and the directions $\stackrel{\circ}{e}_{j}(k)$, but for the calculation of the scattering intensity the lattice factor and therefore the expression $\mathbf{b} . T(k) . \mathbf{b}$ in the general case of oblique cell-edge vectors $\mathbf{a}_{k}$ is needed. Up to now only orthorhombic cells were taken into consideration. In the following the general formula for b. $T(k) . \mathbf{b}$ is derived. As an example the explicit expression for a monoclinic lattice will be given. This special case is of interest in connexion with the small-angle scattering from fibrillar and lamellar superstructures in semicrystalline polymers (Jungnickel, Teichgräber \& Ruscher, 1973).

## 2. Theory

In real space three coordinate systems are used:

1. A basic Cartesian system, unit vectors $\mathbf{e}_{i}$.
2. Principal-axes systems of the fluctuation tensors $T(k)$ with unit vectors $\stackrel{\circ}{\mathbf{e}}_{l}(k)(k=1,2,3)$ (Fig. 1).

The calculations can be done with a common origin of these coordinate systems, because the shift of the tensor ellipsoids to $\mathbf{a}_{k}$ is taken into account by (2).


Fig. 1. Two-dimensional representation of the fluctuation tensor ellipsoids.

The systems $\stackrel{\circ}{\mathbf{e}}_{l}(k)$ are rotated relative to the system $\mathbf{e}_{i}$. The rotations are specified by

The $\stackrel{\circ}{e}_{i}(k)$ and $\mathbf{e}_{l}$ are expressed as

$$
\begin{gather*}
\stackrel{\circ}{\mathbf{e}}_{i}(k)=\sum_{j=1}^{3} \alpha_{l j}(k) \mathbf{e}_{j}:=\alpha_{i j}(k) \mathbf{e}_{j}  \tag{7}\\
\mathbf{e}_{l}=\alpha_{j i}(k) \dot{\mathbf{e}}_{j}(k) \tag{8}
\end{gather*}
$$

3. The lattice system with base vectors $\mathbf{a}_{i}$.

In terms of the Cartesian unit vectors $\mathbf{e}_{i}$, the cell-edge vectors $\mathbf{a}_{l}$ are given by

$$
\begin{equation*}
\mathbf{a}_{i}=\sum_{j=1}^{3} a_{i}^{j} \mathbf{e}_{j}=a_{i}^{j} \mathbf{e}_{j} \tag{9}
\end{equation*}
$$

The elements of the metric tensor $G_{l j}$ (Price, 1982) are defined as

$$
\begin{equation*}
G_{i j}=\mathbf{a}_{i} \cdot \mathbf{a}_{j}=G_{j l} . \tag{10}
\end{equation*}
$$

The base vectors of the reciprocal space are $\mathbf{a}^{i}$. The following relations are valid:

$$
\begin{align*}
\mathbf{a}_{l} \cdot \mathbf{a}^{j} & =\delta_{l}^{j}=\left\{\begin{array}{l}
1 \text { if } i=j \\
0 \text { if } i \neq j
\end{array}\right.  \tag{11}\\
\mathbf{a}^{i} & =G^{i j} \mathbf{a}_{j} \\
& =G^{i j} a_{j}^{l} \mathbf{e}_{l} \\
& =c^{i l} \mathbf{e}_{l} \tag{12}
\end{align*}
$$

where

$$
\begin{equation*}
c^{l l}=G^{i j} a_{j}^{l} \tag{13}
\end{equation*}
$$

The reciprocal-space metric tensor $G^{i j}$ is the inverse of $G_{i j}$ :

$$
\begin{equation*}
G^{i j}=\left(G_{i j}\right)^{-1} \tag{14}
\end{equation*}
$$

A vector in reciprocal space can be written

$$
\begin{equation*}
\mathbf{b}=h_{i} \mathbf{a}^{i} \tag{15}
\end{equation*}
$$

with $h_{i}$ as continuous variables. At the nodes of the reciprocal lattice they become integers (Miller indices). Insertion of (11) in (14) results in

$$
\begin{align*}
\mathbf{b} & =h_{i} c^{i l} \mathbf{e}_{i} \\
& =b^{l} \mathbf{e}_{i}  \tag{16}\\
b^{l} & =h_{i} c^{i l} \\
& =h_{i} G^{i j} a_{j}^{l} \tag{17}
\end{align*}
$$

To calculate $\mathbf{b} . T(k) . \mathbf{b}$, the transformation of $T(k)$ from the principal-axes coordinate system $\dot{\circ}_{l}(k)$ to the basic Cartesian system $\mathrm{e}_{l}$ must be done as a first step. The principal values and the direction of the principal axes are given in the form

$$
\check{T}(k)=\left(\begin{array}{ccc}
\Delta_{11}(k) & 0 & 0  \tag{18}\\
0 & \Delta_{22}(k) & 0 \\
0 & 0 & \Delta_{33}(k)
\end{array}\right)
$$

and

$$
\begin{equation*}
\check{\mathbf{e}}_{i}(k)=\alpha_{i j}(k) \mathbf{e}_{j} . \tag{19}
\end{equation*}
$$

Using the transformation rules for tensor components and bearing in mind the diagonal form of $\check{T}(k)$, one obtains the components $T_{i j}(k)$ expressed in the $\mathbf{e}_{i}$ coordinate system:

$$
\begin{align*}
T_{i j}(k) & =[T(k)]_{l j}=\Delta_{i j}^{2}(k) \\
& =\alpha_{l i}(k) \alpha_{m j}(k) \Delta_{l m}^{2}(k) \\
& =\alpha_{l i}(k) \alpha_{l j}(k) \Delta_{l l}^{2}(k) . \tag{20}
\end{align*}
$$

This result with (16) and (17) allows the calculations of b. $T(k) . \mathbf{b}$ in a straightforward manner:

$$
\begin{align*}
\mathbf{b} . T(k) . \mathbf{b} & =b^{i} \mathbf{e}_{l} \cdot T_{l m}(k) \mathbf{e}_{l} \mathbf{e}_{m} \cdot b^{j} \mathbf{e}_{j} \\
& =b^{i} b^{j} T_{l m}(k) \mathbf{e}_{i} \cdot \mathbf{e}_{l} \mathbf{e}_{m} \cdot \mathbf{e}_{j} \\
& =b^{i} b^{j} T_{i j}(k) \\
& =b^{i} b^{j} \alpha_{l i}(k) \alpha_{i j}(k) J_{l l}^{2}(k) \\
& =h_{m} c^{m i} h_{n} c^{n j} \alpha_{l i}(k) \alpha_{l j}(k) \Delta_{l l}^{2}(k) \\
& =h_{m} G^{m p} a_{p}^{i} h_{n} G^{n q} a_{q}^{j} \alpha_{l l}(k) \alpha_{l j}(k) \Delta_{l l}^{2}(k) \\
& =h_{m} h_{n} G^{m p} G^{n q} a_{p}^{i} a_{q}^{j} \alpha_{l i}(k) \alpha_{l j}(k) \Delta_{l l}^{2}(k)( \tag{21}
\end{align*}
$$

(summation over all repeated indices, regardless of position).
For a specific paracrystalline lattice the values $\Delta_{l l}^{2}(k)$ and $\alpha_{i j}(k)$, which describe the distortion tensor ellipsoids, are fixed. The values of $G^{i j}$ and $a_{i}^{j}$ are determined by the lattice type. The lattice factor is then obtained by inserting (20) into (3) and the resulting $\left|F_{k}(\mathbf{b})\right|$ into (4). For the special case of an orthorhombic lattice and fluctuation tensors with principal axes parallel to the cell-edge vectors $\left[\alpha_{l j}(k)=\delta_{i k}\right]$ we obtain the well known result

$$
\begin{equation*}
\mathbf{b} \cdot T(k) \cdot \mathbf{b}=\frac{U_{l l}^{2}(k)}{\left|\mathbf{a}_{l}\right|^{2}} h_{l}^{2} . \tag{22}
\end{equation*}
$$

## 3. Application to a monoclinic lattice

In some cases the analysis of the small-angle X-ray scattering from oriented semicrystalline polymers can be carried out by using a monoclinic paracrystalline macro lattice as structure model (Jungnickel, Teichgräber \& Ruscher, 1973). The often observed fibrillar and lamellar structures are special cases of such a superlattice (Fig. 2). In the case of uniaxial oriented samples rotational symmetry about the fiber axis ( $a_{3}$ direction) exists and the minimum set of fluctuation tensor componence consists of

$$
\begin{align*}
& \grave{\Delta}_{11}(1)=\Delta_{11}(2)=\Delta_{22}(1)=\dot{\Delta}_{22}(2):=\Delta_{r} \\
& \Delta_{33}(1)=\dot{\Delta}_{33}(2):=\Delta_{a 3} \\
& \Delta_{33}(3)=\Delta_{33} \\
& \Delta_{11}(3)=\Delta_{22}(3)=0 . \tag{23}
\end{align*}
$$

Furthermore, we set $\left|\mathbf{a}_{1}\right| \sin \beta=\left|\mathbf{a}_{2}\right|$ because of the rotational symmetry.

To characterize the statistical fluctuations of a paracrystalline lattice usually the relative fluctuations

$$
\begin{align*}
\frac{\Delta_{r}}{\left|\mathbf{a}_{1}\right| \sin \beta}=\frac{\Delta_{r}}{\left|\mathbf{a}_{2}\right|} & =g_{r},  \tag{24}\\
\frac{\Delta_{33}}{\left|\mathbf{a}_{3}\right|} & =g_{33},  \tag{25}\\
\frac{\Delta_{3}}{\left|\mathbf{a}_{3}\right|} & =g_{3} \tag{26}
\end{align*}
$$

are introduced.
A fibrillar structure is defined by $g_{3} \gg g_{33}$ (for isolated fibrils ( $g_{3}$ and $g_{r}$ ) $>g_{33}$ l and a lamellar structure by $g_{3} \ll 1$.

The edge vectors of the monoclinic lattice cell relative to the basic Cartesian coordinate system are chosen in the following way:

$$
\begin{align*}
& \mathbf{a}_{1}=a_{1}^{1} \mathbf{e}_{1}+\mathbf{a}_{1}^{3} \mathbf{e}_{3}  \tag{27}\\
& \mathbf{a}_{2}=a_{2}^{2} \mathbf{e}_{2}=\left|\mathbf{a}_{2}\right| \mathbf{e}_{2}  \tag{28}\\
& \mathbf{a}_{3}=a_{3}^{3} \mathbf{e}_{3}=\left|\mathbf{a}_{3}\right| \mathbf{e}_{3},
\end{align*}
$$

where

$$
\begin{align*}
& a_{1}^{1}=\left|\mathbf{a}_{1}\right| \sin \beta=\left|\mathbf{a}_{2}\right|  \tag{29}\\
& a_{1}^{3}=\left|\mathbf{a}_{1}\right| \cos \beta \tag{30}
\end{align*}
$$

and $\beta=\angle\left(\mathbf{a}_{1}, \mathbf{a}_{3}\right)$.
The reciprocal-space metric tensor follows from (10) and (14):


Fig. 2. Schematic representation of paracrystalline monoclinic macro lattices: lamellar (left) and fibrillar (right) structure.

$$
\left.G^{i j}=\left\lvert\, \begin{array}{ccc}
\frac{1}{\left|\mathbf{a}_{1}\right|^{2} \sin ^{2} \beta} & 0 & -\frac{\cos \beta}{\left|\mathbf{a}_{1}\right|\left|\mathbf{a}_{3}\right| \sin ^{2} \beta}  \tag{31}\\
0 & \frac{1}{\left|\mathbf{a}_{2}\right|^{2}} & 0 \\
-\frac{\cos \beta}{\left|\mathbf{a}_{1}\right|\left|\mathbf{a}_{3}\right| \sin ^{2} \beta} & 0 & \frac{1}{\left|\mathbf{a}_{3}\right|^{2} \sin ^{2} \beta}
\end{array}\right.\right)
$$

The reciprocal-lattice vectors are calculated with (12) and (27)-(31):

$$
\begin{align*}
\mathbf{a}^{1} & =G^{11} \mathbf{a}_{1}+G^{12} \mathbf{a}_{2}+G^{13} \mathbf{a}_{3} \\
& =\frac{1}{\left|\mathbf{a}_{1}\right| \sin \beta} \mathbf{e}_{1} . \tag{32}
\end{align*}
$$

In a similar way results for $\mathbf{a}^{\mathbf{2}}$ and $\mathbf{a}^{\mathbf{3}}$

$$
\begin{align*}
& \mathbf{a}^{2}=\frac{1}{\left|a_{2}\right|} \cdot e_{2}  \tag{33}\\
& \mathbf{a}^{3}=-\frac{\cot \beta}{\left|a_{3}\right|} e_{1}+\frac{1}{a_{3}} \cdot e_{3} . \tag{34}
\end{align*}
$$

The vector $\mathbf{b}$ is obtained by inserting (32)-(34) into (15):

$$
\begin{align*}
\mathbf{b}= & h_{1} \mathbf{a}^{1}+h_{2} \mathbf{a}^{2}+h_{3} \mathbf{a}^{3} \\
= & {\left[\frac{h_{1}}{\left|\mathbf{a}_{1}\right| \sin \beta}-\frac{h_{3} \cot \beta}{\left|\mathbf{a}_{3}\right|}\right] \cdot \mathbf{e}_{1} } \\
& +\frac{h_{2}}{\left|\mathbf{a}_{2}\right|} \cdot \mathbf{e}_{2}+\frac{h_{3}}{\left|\mathbf{a}_{3}\right|} \cdot \mathbf{e}_{3} . \tag{35}
\end{align*}
$$

The directions $\stackrel{\circ}{e}_{1}(k)$ of the principal axes of the fluctuation tensors for the case in question must be fixed parallel to the unit vectors $\mathbf{e}_{i}$ of the basic Cartesian system, hence [compare with (8)],

$$
\begin{equation*}
\alpha_{i j}(k)=\delta_{i j} \tag{36}
\end{equation*}
$$

Equation (21) reduces to

$$
\text { b. } \begin{align*}
T(k) \cdot \mathbf{b} & =h_{m} h_{n} G^{m p} G^{n q} a_{p}^{i} a_{q}^{j} \delta_{l i} \delta_{l j} \delta_{l l}^{2}(k) \\
& =h_{m} h_{n} G^{m p} G^{n q} a_{p}^{l} a_{q}^{l} \dot{J}_{l l}^{2}(k) \tag{37}
\end{align*}
$$

As an example, the calculation of $\mathbf{b} . T(3) . \mathbf{b}$ is worked out in the following.

$$
\begin{align*}
\mathbf{b . T ( 3 ) . \mathbf { b } =} & h_{m} h_{n} G^{m p} G^{n q} a_{p}^{3} a_{q}^{3} \Delta_{33}^{2} \\
= & \Delta_{33}^{2} h_{m} h_{n} G^{m p} a_{p}^{3}\left(G^{n 1} a_{1}^{3}+G^{n 3} a_{3}^{3}\right) \\
= & \Delta_{33}^{2} h_{m} h_{n}\left(G^{n 1} a_{1}^{3}+G^{n 3} a_{3}^{3}\right) \\
& \times\left(G^{m 1} a_{1}^{3}+G^{m 3} a_{1}^{3}\right) \\
= & \Delta_{33}^{2}\left[h_{1} G^{11} a_{1}^{3}+h_{1} G^{13} a_{3}^{3}+h_{3}\right. \\
& \left.\times G^{31} a_{1}^{3}+h_{3} G^{33} a_{3}^{3}\right]^{2} \\
= & \Delta_{33}^{2}\left[\frac{h_{3}\left(1-\cos ^{2} \beta\right)}{\left|\mathbf{a}_{3}\right| \sin ^{2} \beta}\right]^{2} \\
= & \frac{\Delta_{33}^{2}}{\left|\mathbf{a}_{3}\right|^{2}} h_{3}^{2}=g_{33}^{2} h_{3}^{2} . \tag{38}
\end{align*}
$$

In the same way, but by a more lengthy calculation, the formula for $\mathbf{b} \cdot T(1) \cdot \mathbf{b}=\mathbf{b} \cdot T(2) \cdot \mathbf{b}$ is obtained:
b. $T(1) \cdot \mathbf{b}=\mathbf{b} \cdot T(2) \cdot \mathbf{b}$

$$
\begin{equation*}
=g_{r}^{2}\left\{\left[h_{1}-\frac{\left|\mathbf{a}_{1}\right| \cos \beta}{\left|\mathbf{a}_{3}\right|} h_{3}\right]^{2}+h_{2}^{2}\right\}+g_{3}^{2} h_{3}^{2} \tag{39}
\end{equation*}
$$

Finally, in the denominator of the lattice factor $Z(\mathbf{b})$ the term proportional to $\sin ^{2}\left[\pi\left(\mathbf{b} . \mathbf{a}_{k}\right)\right]$ occurs and must be written as a function of the variables $h_{i}$. The result follows immediately from (11) and (15):

$$
\begin{equation*}
\mathbf{b} \cdot \mathbf{a}_{k}=h_{k} . \tag{40}
\end{equation*}
$$

The explicit formula for the lattice factor $Z(b)$ follows from (38)-(40) together with (3) and (4). The smallangle scattering intensity is obtained by specifying the bricks of the lattice (e.g. cylindrical crystallites) and working out some averaging processes (Wilke \& Göttlicher, 1981). The details of this procedure are outside the scope of this paper.

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